



Scalable Unbalanced Optimal Transport by Slicing

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Séminaire Monge – Université Gustave Eiffel April 18, 2024

"Balanced" Optimal Transport

 $\mathcal{M}^1_+(\mathbb{R}^d)$: set of probability measures on \mathbb{R}^d

For $(\alpha, \beta) \in \mathcal{M}^1_+(\mathbb{R}^d) \times \mathcal{M}^1_+(\mathbb{R}^d)$, $OT(\alpha, \beta) \triangleq \inf_{\pi \in \Gamma(\alpha, \beta)} \int_{\mathbb{R}^d \times \mathbb{R}^d} C(x, y) \, \mathrm{d}\pi(x, y)$ $\Gamma(\alpha, \beta) \triangleq \left\{ \pi \in \mathcal{M}^1_+(\mathbb{R}^d \times \mathbb{R}^d) \text{ with marginals } (\pi_1, \pi_2) = (\alpha, \beta) \right\}$

Limitations:

- Restricted to *probability* measures
- Lack of robustness to *outliers*

Unbalanced Optimal Transport

 $\mathcal{M}_+(\mathbb{R}^d)$: set of positive Radon measures on \mathbb{R}^d

Unbalanced OT (static formulation) [Liero et al., 2018]

For
$$(\alpha, \beta) \in \mathcal{M}_{+}(\mathbb{R}^{d}) \times \mathcal{M}_{+}(\mathbb{R}^{d}),$$

$$\operatorname{UOT}(\alpha, \beta) \triangleq \inf_{\pi \in \mathcal{M}_{+}(\mathbb{R}^{d} \times \mathbb{R}^{d})} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \operatorname{C}(x, y) \, \mathrm{d}\pi(x, y) + \operatorname{D}_{\rho\varphi_{1}}(\pi_{1}|\alpha) + \operatorname{D}_{\rho\varphi_{2}}(\pi_{2}|\beta)$$

φ -divergences

$$\mathbf{D}_{\varphi}(\boldsymbol{\alpha}|\boldsymbol{\beta}) \triangleq \int_{\mathbb{R}^d} \varphi\left(\frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}\boldsymbol{\beta}}(x)\right) \mathrm{d}\boldsymbol{\beta}(x) + \varphi_{\infty}' \int_{\mathbb{R}^d} \mathrm{d}\boldsymbol{\alpha}^{\perp}(x)$$

 φ "entropy function", $\varphi'_{\infty} \triangleq \lim_{x \to +\infty} \varphi(x)/x$. $\alpha = (\mathrm{d}\alpha/\mathrm{d}\beta)\beta + \alpha^{\perp}$

Examples: Kullback-Leibler divergence (KL, $\varphi(t) = t \log(t) - t + 1$), Total Variation (TV, $\varphi(t) = |t - 1|$)

Balanced vs. Unbalanced OT



Figure from: T. Séjourné, G. Peyré, and F.-X. Vialard. Unbalanced optimal transport, from theory to numerics. 2022

Solving (unbalanced) OT in practice

Solving OT

- Linear programming
- Entropic regularization [Cuturi, 2013]
- Slicing [Rabin et al., 2011]

Solving unbalanced OT

- Various strategies, reviewed in [Séjourné et al., 2022]
- Entropic regularization [Chizat et al., 2018]
- Translation-invariant dual formulation + Frank-Wolfe strategy [Séjourné et al., 2022]
- Slicing \rightarrow for one specific setting and lack of theoretical insights [Bai et al., 2022]

Background on Sliced Optimal Transport

Optimal Transport in 1D

For $(\alpha, \beta) \in \mathcal{M}_{+}(\mathbb{R}) \times \mathcal{M}_{+}(\mathbb{R}),$ $\operatorname{OT}(\alpha, \beta) = \int_{0}^{1} \left| F_{\alpha}^{-1}(t) - F_{\beta}^{-1}(t) \right| \mathrm{d}t$

 $F_{\alpha}^{-1}, F_{\beta}^{-1}$: quantile functions of α, β [Rachev and Rüschendorf, 1998]



Figure inspired by [Peyré and Cuturi, 2019]

$$OT(\alpha, \beta) = \frac{1}{n} \sum_{i=1}^{n} |\boldsymbol{x}_{(i)} - \boldsymbol{y}_{(i)}|$$

with $x_{(1)} \leq x_{(2)} \leq \cdots \leq x_{(n)}$, $y_{(1)} \leq y_{(2)} \leq \cdots \leq y_{(n)}$ $\Rightarrow \mathcal{O}(n \log(n))$ operations

Slicing Distributions



 $\theta_{\sharp}^{\star}\beta$ is the *pushforward measure* of β by θ^{\star} , with $\theta^{\star}: \mathbb{R}^{d} \to \mathbb{R}, \quad \theta^{\star}(y) = \langle \theta, y \rangle$

Slicing OT

Sliced OT [Rabin et al., 2011] $\mathbb{S}^{d-1} \triangleq \{\theta \in \mathbb{R}^{d} : \|\theta\| = 1\} \text{ with uniform measure } \boldsymbol{\sigma}$ For $\theta \in \mathbb{S}^{d-1}, \theta^{\star} : \mathbb{R}^{d} \to \mathbb{R} \text{ s.t. } \forall x \in \mathbb{R}^{d}, \theta^{\star}(x) \triangleq \langle \theta, x \rangle$ For $(\boldsymbol{\alpha}, \beta) \in \mathcal{M}_{+}(\mathbb{R}^{d}) \times \mathcal{M}_{+}(\mathbb{R}^{d}),$ $\operatorname{SOT}(\boldsymbol{\alpha}, \beta) \triangleq \int_{\mathbb{S}^{d-1}} \operatorname{OT}(\theta_{\sharp}^{\star}\boldsymbol{\alpha}, \theta_{\sharp}^{\star}\beta) \mathrm{d}\boldsymbol{\sigma}(\theta)$

with $\theta_{\sharp}^{\star} \alpha$, $\theta_{\sharp}^{\star} \beta$: pushforward measures of α , β by θ^{\star}

Monte Carlo approximation based on $\theta_1, \ldots, \theta_K \stackrel{i.i.d}{\sim} \boldsymbol{\sigma}$

$$\Rightarrow \mathcal{O}\left(\underbrace{Kdn}_{\text{projecting}} + \underbrace{Kn\log(n)}_{\text{sorting}}\right) \text{ operations}$$

Sliced OT

Various applications

- Barycenters of measures [Rabin et al., 2012; Bonneel et al., 2015]
- Kernel functions for topological data analysis, pattern recognition [Kolouri et al., 2016; Carrière et al., 2017]
- Generative modeling [Kolouri et al., 2018; Deshpande et al., 2018; Liutkus et al., 2019; Wu et al., 2019; Kolouri et al., 2019b; Dai and Seljak, 2021]

Theoretical analysis

- Metric axioms and equivalence with OT [Bonnotte, 2013]
- Convergence guarantees [Nadjahi et al., 2019; Xi and Niles-Weed, 2022; Tanguy et al., 2024]
- Sample complexity [Manole et al., 2019; Nadjahi et al., 2020]
- Sliced-OT flows [Park and Slepčev, 2023]

Extensions [Kolouri et al., 2019a; Deshpande et al., 2019; Ohana et al., 2023; Nguyen et al., 2021]

Scalable Unbalanced Optimal Transport by Slicing

Towards Slicing Unbalanced OT

For $\varphi : \mathbb{R} \to \mathbb{R}$ convex, denote by φ^* its Legendre transform, i.e.,

$$\forall x \in \mathbb{R}, \quad \varphi^*(x) \triangleq \sup_{y \in \mathbb{R}} xy - \varphi(y)$$

Strong duality [Liero et al., 2018]
For
$$(\alpha, \beta) \in \mathcal{M}_{+}(\mathbb{R}^{d}) \times \mathcal{M}_{+}(\mathbb{R}^{d}),$$

 $\operatorname{UOT}(\alpha, \beta) = \sup_{f \oplus g \leq C} \mathcal{D}(f, g)$
with $\mathcal{D}(f, g) \triangleq -\int \varphi_{1}^{*}(-f(x)) \mathrm{d}\alpha(x) - \int \varphi_{2}^{*}(-g(y)) \mathrm{d}\beta(y)$

UOT is not invariant to translation [Séjourné et al., 2022]

- Given $\lambda \in \mathbb{R}$, one may have $\mathcal{D}(f + \lambda, g \lambda) \neq \mathcal{D}(f, g)$
- This can slow down the computation of $\mathrm{UOT}(\alpha,\beta)$

Towards Slicing Unbalanced OT

Strong duality [Liero et al., 2018] For $(\alpha, \beta) \in \mathcal{M}_+(\mathbb{R}^d) \times \mathcal{M}_+(\mathbb{R}^d)$, $\operatorname{UOT}(\alpha, \beta) = \sup_{f \oplus g \leq C} \mathcal{D}(f, g)$ with $\mathcal{D}(f, g) \triangleq \int \varphi_1^{\circ}(f(x)) \mathrm{d}\alpha(x) + \int \varphi_2^{\circ}(g(y)) \mathrm{d}\beta(y)$

Translation-invariant (TI) dual [Séjourné et al., 2022] For $(\alpha, \beta) \in \mathcal{M}_{+}(\mathbb{R}^{d}) \times \mathcal{M}_{+}(\mathbb{R}^{d}),$ $\operatorname{UOT}(\alpha, \beta) = \sup_{f \oplus g \leq C} \mathcal{H}(f, g)$ (1) with $\mathcal{H}(f, g) \triangleq \sup_{\lambda \in \mathbb{R}} \mathcal{D}(f + \lambda, g - \lambda)$

1-D UOT: Frank-Wolfe algorithm to solve (1) [Séjourné et al., 2022] $\Rightarrow \mathcal{O}(Tn \log(n))$ operations, with T: number of F-W iterations

Slicing and Unbalancing Optimal Transport

We propose two strategies [Séjourné et al., 2023]

Sliced Unbalanced OT

For $(\boldsymbol{\alpha}, \boldsymbol{\beta}) \in \mathcal{M}_+(\mathbb{R}^d) \times \mathcal{M}_+(\mathbb{R}^d)$,

$$\mathrm{SUOT}(\boldsymbol{\alpha},\boldsymbol{\beta}) \triangleq \int_{\mathbb{S}^{d-1}} \mathrm{UOT}(\theta_{\sharp}^{\star}\boldsymbol{\alpha},\theta_{\sharp}^{\star}\boldsymbol{\beta}) \mathrm{d}\boldsymbol{\sigma}(\boldsymbol{\theta})$$

$$\mathrm{UOT}(\theta_{\sharp}^{\star}\alpha,\theta_{\sharp}^{\star}\beta) = \inf_{\pi_{\theta}\in\mathcal{M}_{+}(\mathbb{R}\times\mathbb{R})} \int \mathrm{C}(x,y) \,\mathrm{d}\pi_{\theta}(x,y) + \mathrm{D}_{\varphi_{1}}((\pi_{\theta})_{1}|\theta_{\sharp}^{\star}\alpha) + \mathrm{D}_{\varphi_{2}}((\pi_{\theta})_{2}|\theta_{\sharp}^{\star}\beta)$$

Unbalanced Sliced OT

For $(\boldsymbol{\alpha}, \boldsymbol{\beta}) \in \mathcal{M}_+(\mathbb{R}^d) \times \mathcal{M}_+(\mathbb{R}^d),$

$$\mathrm{USOT}(\alpha,\beta) \triangleq \inf_{(\pi_1,\pi_2) \in \mathcal{M}_+(\mathbb{R}^d)^2} \mathrm{SOT}(\pi_1,\pi_2) + \mathrm{D}_{\varphi_1}(\pi_1|\alpha) + \mathrm{D}_{\varphi_2}(\pi_2|\beta)$$

Slicing Unbalanced vs. Unbalancing Sliced

SUOT: generalization of sliced partial OT [Bai et al., 2022], particular case of sliced divergences [Nadjahi et al., 2020]

USOT: new!



Figure 1: (*left*) input distributions; (*middle*) $(\pi_{\theta})_1, (\pi_{\theta})_2$ by SUOT; (*right*) $\theta_{\sharp}^* \pi_1, \theta_{\sharp}^* \pi_2$ by USOT; projected distributions in grey

Theoretical Properties

Existence of solutions

Under mild assumptions on C and (φ_1, φ_2) , the solution of USOT (α, β) and SUOT (α, β) exist, *i.e.*,

- There exists π attaining the infimum in USOT (α, β)
- For $\theta \in \mathbb{S}^{d-1}$, there exists π_{θ} attaining the inf. in $\text{UOT}(\theta_{\sharp}^{\star} \alpha, \theta_{\sharp}^{\star} \beta)$

Metric axioms

- UOT is a (pseudo-)metric on $\mathbb{R} \Rightarrow$ SUOT is a (pseudo-)metric on \mathbb{R}^d (consistent with [Nadjahi et al., 2020])
- USOT is a pseudo-metric on \mathbb{R}^d

Theoretical Properties

Equivalence

$$\operatorname{SUOT}(\alpha, \beta) \leq \operatorname{USOT}(\alpha, \beta) \leq \operatorname{UOT}(\alpha, \beta)$$

If $(\alpha, \beta) \in \mathcal{M}_+(\mathsf{X}) \times \mathcal{M}_+(\mathsf{X})$ with $\mathsf{X} \subseteq \mathbb{R}^d$ compact, and $\mathsf{D}_{\varphi_1} = \mathsf{D}_{\varphi_2} = \rho \mathsf{KL}$ or $\rho \mathsf{TV}$,

 $\operatorname{UOT}(\boldsymbol{\alpha}, \boldsymbol{\beta}) \leq c \operatorname{SUOT}(\boldsymbol{\alpha}, \boldsymbol{\beta})^{\frac{1}{d+1}}$

with c: constant depending on $(\rho, \operatorname{radius}(X), m(\alpha), m(\beta))$

 \Rightarrow Equivalence of SUOT, USOT and UOT if $m(\alpha), m(\beta) \leq M$

Weak^{*} metrization

Under the same assumptions,

$$\alpha_n \rightharpoonup \alpha \iff \lim_{n \to +\infty} \operatorname{SUOT}(\alpha_n, \alpha) = 0 \iff \lim_{n \to +\infty} \operatorname{USOT}(\alpha_n, \alpha) = 0$$

Statistical Efficiency



Sample complexity: $\mathbb{E}[|\mathcal{L}(\hat{\alpha}_n, \hat{\beta}_n) - \mathcal{L}(\alpha, \beta)|]$ vs. n, with $\mathcal{L} =$ SUOT or USOT and $\alpha = \beta = \mathcal{N}(\mathbf{0}_d, \mathbf{I}_d)$

 \Rightarrow Convergence rate in $\mathcal{O}(1/n)$ for any dimension d

Strong Duality

- $(\alpha, \beta) \in \mathcal{M}_+(\mathbb{R}^d) \times \mathcal{M}_+(\mathbb{R}^d)$
- $\varphi_i^{\circ}(x) \triangleq -\varphi_i^{*}(-x)$, with φ_i^{*} : Legendre transform of φ_i

Primal problems

$$UOT(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \inf_{(\pi_1, \pi_2) \in \mathcal{M}_+(\mathbb{R}^d)^2} OT(\pi_1, \pi_2) + D_{\varphi_1}(\pi_1 | \boldsymbol{\alpha}) + D_{\varphi_2}(\pi_2 | \boldsymbol{\beta})$$

$$SUOT(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \int_{\mathbb{S}^{d-1}} UOT(\theta_{\sharp}^{\star} \boldsymbol{\alpha}, \theta_{\sharp}^{\star} \boldsymbol{\beta}) d\boldsymbol{\sigma}(\theta)$$

$$USOT(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \inf_{(\pi_1, \pi_2) \in \mathcal{M}_+(\mathbb{R}^d)^2} SOT(\pi_1, \pi_2) + D_{\varphi_1}(\pi_1 | \boldsymbol{\alpha}) + D_{\varphi_2}(\pi_2 | \boldsymbol{\beta})$$

Strong duality

$$\begin{aligned} \operatorname{UOT}(\alpha,\beta) &= \sup_{f \oplus g \leq C} \langle \varphi_1^{\circ} \circ f, \alpha \rangle + \langle \varphi_2^{\circ} \circ g, \beta \rangle \\ \operatorname{SUOT}(\alpha,\beta) &= \sup_{f_{\theta_k} \oplus g_{\theta_k} \leq C} \frac{1}{K} \sum_{k=1}^{K} \left[\left\langle \varphi_1^{\circ} \circ f_{\theta_k}, (\theta_k^{\star})_{\sharp} \alpha \right\rangle + \left\langle \varphi_2^{\circ} \circ g_{\theta_k}, (\theta_k^{\star})_{\sharp} \beta \right\rangle \right] \\ \operatorname{USOT}(\alpha,\beta) &= \sup_{f_{\theta_k} \oplus g_{\theta_k} \leq C} \langle \varphi_1^{\circ} \circ (\frac{1}{K} \sum_{k=1}^{K} f_{\theta_k}), \alpha \rangle + \langle \varphi_2^{\circ} \circ (\frac{1}{K} \sum_{k=1}^{K} g_{\theta_k}), \beta \rangle \end{aligned}$$

Computing Sliced Unbalanced (and *vice versa*) OT with the Frank-Wolfe Algorithm

Solving Sliced Unbalanced OT

Frank-Wolfe algorithm

 $\min_{x\in\mathsf{X}}h(x)$

 $\mathsf{X} \subseteq \mathbb{R}^d$ compact and convex, $h : \mathsf{X} \to \mathbb{R}$ convex and differentiable

Initialize $x^{(0)} \in X$

Repeat for $t = 1, \ldots, T$

$$y^{(t)} \leftarrow \operatorname*{argmin}_{y \in \mathsf{X}} \langle y, \nabla h(x^{(t)}) \rangle$$

 $x^{(t+1)} \leftarrow (1 - \gamma_t) x^{(t)} + \gamma_t y^{(t)}$

Return $h(x^{(T)})$

Application: Solving $SUOT(\alpha, \beta)$

 $\max_{f_k \oplus g_k \leq \mathcal{C}} \mathcal{H}(f_k, g_k)$

with \mathcal{H} the translation-invariant dual of $\operatorname{UOT}((\theta_k^{\star})_{\sharp}\alpha, (\theta_k^{\star})_{\sharp}\beta)$

Initialize $(f_k^{(0)}, g_k^{(0)})$ s.t. $f_k^{(0)} \oplus g_k^{(0)} \le C$

Repeat for $t = 1, \ldots, T$

$$(r_k^{(t)}, s_k^{(t)}) \gets \operatorname*{argmax}_{r \oplus s \leq \mathcal{C}} \langle (r, s), \nabla \mathcal{H}(f_k^{(t)}, g_k^{(t)}) \rangle$$

$$(f_k^{(t+1)}, g_k^{(t+1)}) \leftarrow (1 - \gamma_t)(f_k^{(t)}, g_k^{(t)}) + \gamma_t(r_k^{(t)}, s_k^{(t)})$$

Return $\frac{1}{K}\sum_{k=1}^{K}\mathcal{H}(f_k^{(T)},g_k^{(T)})$

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Solving Sliced Unbalanced OT

w If

Translation-invariant dual of $UOT(\theta_{\sharp}^{\star}\alpha, \theta_{\sharp}^{\star}\beta)$

$$\mathcal{H}(f_{\theta}, g_{\theta}) = \sup_{\lambda \in \mathbb{R}} \mathcal{D}(f_{\theta} + \lambda, g_{\theta} - \lambda)$$

ith $\mathcal{D}(f_{\theta}, g_{\theta}) = \langle \varphi_{1}^{\circ} \circ f_{\theta}, \theta_{\sharp}^{\star} \alpha \rangle + \langle \varphi_{2}^{\circ} \circ g_{\theta}, \theta_{\sharp}^{\star} \beta \rangle$
 $D_{\varphi_{1}} = D_{\varphi_{2}} = \rho \text{KL},$
 $\lambda_{\theta}^{\star} \triangleq \operatorname{argmax}_{\lambda \in \mathbb{R}} \mathcal{D}(f_{\theta} + \lambda, g_{\theta} - \lambda) = \frac{\rho^{2}}{2\rho} \log \left(\frac{\langle e^{-f_{\theta}/\rho}, \theta_{\sharp}^{\star} \alpha \rangle}{\langle e^{-g_{\theta}/\rho}, \theta_{\sharp}^{\star} \beta \rangle} \right)$
 $\nabla \mathcal{H}(f_{\theta}, g_{\theta}) = \underbrace{(\nabla \varphi_{1}^{\circ}(f_{\theta} + \lambda_{\theta}^{\star}) \theta_{\sharp}^{\star} \alpha}_{\tilde{\alpha}_{\theta}}, \nabla \underbrace{\varphi_{2}^{\circ}(g_{\theta} - \lambda_{\theta}^{\star}) \theta_{\sharp}^{\star} \beta}_{\tilde{\beta}_{\theta}}$

where $\tilde{\alpha}_{\theta}, \, \tilde{\beta}_{\theta}$ have the same mass

$$(r_k^{(t)}, s_k^{(t)}) = \operatorname*{argmax}_{r \oplus s \leq \mathcal{C}} \langle (r, s), \nabla \mathcal{H}(f_k^{(t)}, g_k^{(t)}) \rangle = \operatorname*{argmax}_{r \oplus s \leq \mathcal{C}} \langle r, \tilde{\alpha}_{\theta_k} \rangle + \langle s, \tilde{\beta}_{\theta_k} \rangle$$

Frank-Wolfe step \Leftrightarrow **Solving** $OT(\tilde{\alpha}_{\theta_k}, \tilde{\beta}_{\theta_k}), k = 1, ..., K$ \Rightarrow Overall computational complexity in $\mathcal{O}(TKn \log n)$

Solving Unbalanced Sliced OT

Frank-Wolfe algorithm

$$\min_{x \in \mathsf{X}} h(x)$$

 $\mathsf{X} \subseteq \mathbb{R}^d \text{ compact and convex,} \\ h : \mathsf{X} \to \mathbb{R} \text{ convex and differ-} \\ \text{entiable} \end{cases}$

Initialize $x^{(0)} \in X$

Repeat for $t = 1, \ldots, T$

$$y^{(t)} \leftarrow \operatorname*{argmin}_{y \in \mathsf{X}} \langle y, \nabla h(x^{(t)}) \rangle$$

$$x^{(t+1)} \leftarrow (1 - \gamma_t) x^{(t)} + \gamma_t y^{(t)}$$

Application: Solving $USOT(\alpha, \beta)$

$$\lim_{\bar{f}=\frac{1}{K}\sum_{k=1}^{K}f_k, \ \bar{g}=\frac{1}{K}\sum_{k=1}^{K}g_k, \ \mathcal{H}(\bar{f},\bar{g})}{f_k\oplus g_k\leq C}$$

with \mathcal{H} the translation-invariant dual of $USOT(\alpha, \beta)$

Initialize
$$(f_k^{(0)}, g_k^{(0)})$$
 s.t. $f_k^{(0)} \oplus g_k^{(0)} \le C$
Repeat for $t = 1, \dots, T$

$$(\bar{r}^{(t)}, \bar{s}^{(t)}) \leftarrow \underset{\substack{\bar{r} = \frac{1}{K} \sum_{k=1}^{K} r_k, \\ \bar{s} = \frac{1}{K} \sum_{k=1}^{K} s_k, \\ r_k \oplus s_k \leq \mathbf{C} } \langle (\bar{r}, \bar{s}), \nabla \mathcal{H}(\bar{f}^{(t)}, \bar{g}^{(t)}) \rangle$$

 $(\bar{f}^{(t+1)}, \bar{g}^{(t+1)}) \leftarrow (1-\gamma_t)(\bar{f}^{(t)}, \bar{g}^{(t)}) + \gamma_t(\bar{r}^{(t)}, \bar{s}^{(t)})$

Return $\mathcal{H}(\bar{f}^{(T)}, \bar{g}^{(T)})$

Return $h(x^{(T)})$

Solving Unbalanced Sliced OT

Translation-invariant dual of $USOT(\alpha, \beta)$

$$\mathcal{H}(\bar{f},\bar{g}) = \sup_{\lambda \in \mathbb{R}} \mathcal{D}(\bar{f} + \lambda, \bar{g} - \lambda)$$

with $\mathcal{D}(\bar{f},\bar{g}) = \langle \varphi_1^{\circ} \circ \bar{f}, \alpha \rangle + \langle \varphi_2^{\circ} \circ \bar{g}, \beta \rangle$
If $D_{\varphi_1} = D_{\varphi_2} = \rho KL$,
 $\bar{\lambda}^* \triangleq \operatorname{argmax}_{\lambda \in \mathbb{R}} \mathcal{D}(\bar{f} + \lambda, \bar{g} - \lambda) = \frac{\rho^2}{2\rho} \log \left(\frac{\langle e^{-\bar{f}/\rho}, \alpha \rangle}{\langle e^{-\bar{g}/\rho}, \beta \rangle} \right)$
 $\nabla \mathcal{H}(\bar{f},\bar{g}) = (\underbrace{\nabla \varphi_1^{\circ}(\bar{f} + \bar{\lambda}^*)\alpha}_{\bar{\alpha}}, \nabla \underbrace{\varphi_2^{\circ}(\bar{g} - \bar{\lambda}^*)\beta}_{\bar{\beta}})$

where $\tilde{\alpha}, \tilde{\beta}$ have the same mass

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$$(\bar{r}^{(t)}, \bar{s}^{(t)}) = \operatorname*{argmax}_{r_k \oplus s_k \leq \mathcal{C}} \langle (\bar{r}, \bar{s}), \nabla \mathcal{H}(\bar{f}^{(t)}, \bar{g}^{(t)}) \rangle = \operatorname*{argmax}_{r_k \oplus s_k \leq \mathcal{C}} \langle \bar{r}, \tilde{\alpha} \rangle + \langle \bar{s}, \tilde{\beta} \rangle$$

Frank-Wolfe step \Leftrightarrow **Solving** $OT((\theta_k^{\star})_{\sharp}\tilde{\alpha}, (\theta_k^{\star})_{\sharp}\tilde{\beta}), k = 1, \dots, K$ \Rightarrow Overall computational complexity in $\mathcal{O}(TKn \log n)$

Experiments

Color Transfer



(1st and 2nd columns) Source and target
(3rd column) SOT gradient flow
(4th column) USOT gradient flow
(last) % of mass change by USOT (red: mass creation, blue destruction)

Barycenters for Geophysical Data



(*First row*) 4 climate models (different evolutions of a tropical cyclone) (*Second row*) Different barycenters

Conclusion

Our contributions

- Definition of two new losses merging unbalanced and sliced OT
- Theoretical analysis
- Efficient and modular Frank-Wolfe algorithm
- Encouraging empirical results

Some perspectives

- Open theoretical questions (sample complexity for USOT? Strong duality for σ ?)
- Address new large-scale applications (challenge: sensitivity to ρ in $D_{\varphi}=\rho KL)$

Link to paper: https://arxiv.org/abs/2306.07176

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